

Adaptation to multi tasks by reflecting person hope degree for importance

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- Dynamically reflect a person need a task among robot's multi tasks for importance to robot
- Person need for a task importance is generated by degree using person-robot interaction
- This degree is generated based on predictability of input as Achievement request degree

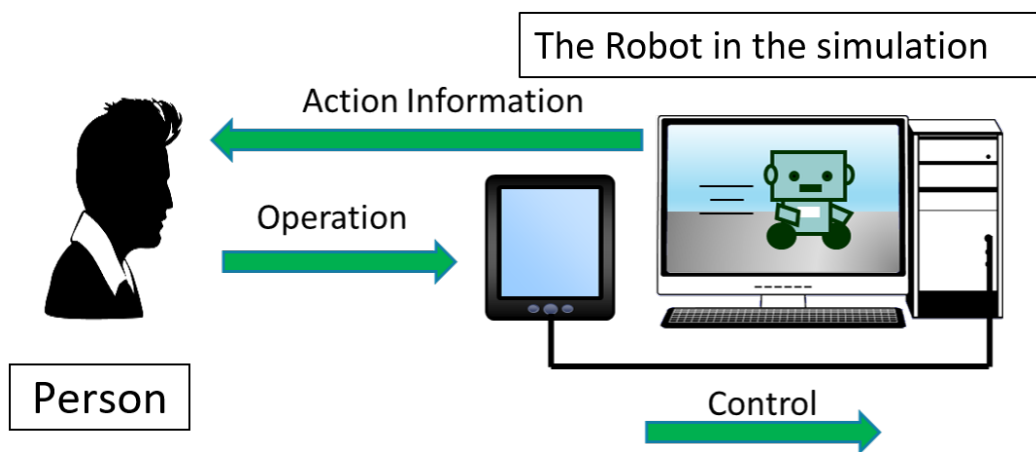


Figure1 Person-robot interaction

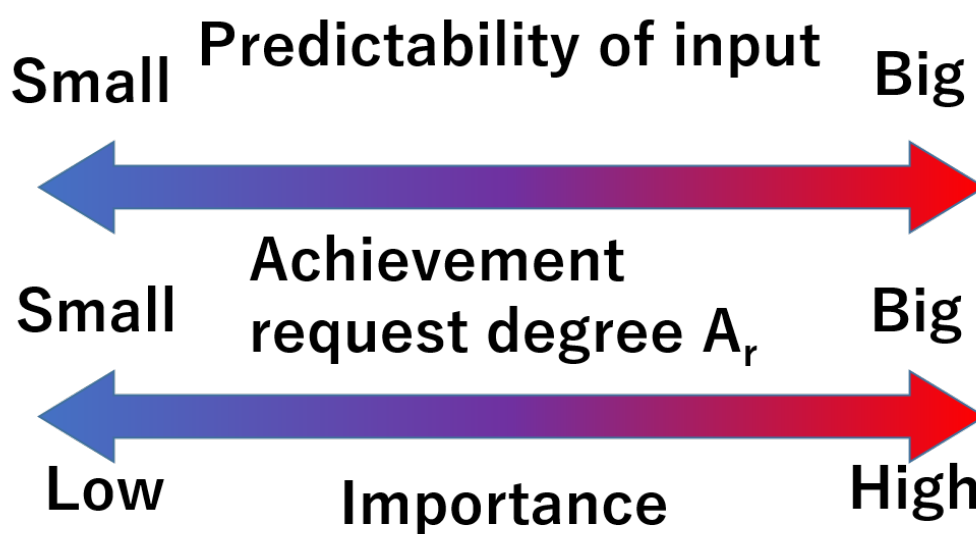


Figure2 Achievement request degree schematic