

Decision Making on Robot using Motivation-Desire Model ~ Autonomous Acquisition the Tasks Based on Correlation between Reward and Sensor ~

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- A robot makes a decision using Motivation-Desire Model
- Generate the reward function based on correlation between the primitive reward and sensors
- Improve an efficiency on learning by Generateion the reward function suitable for environment

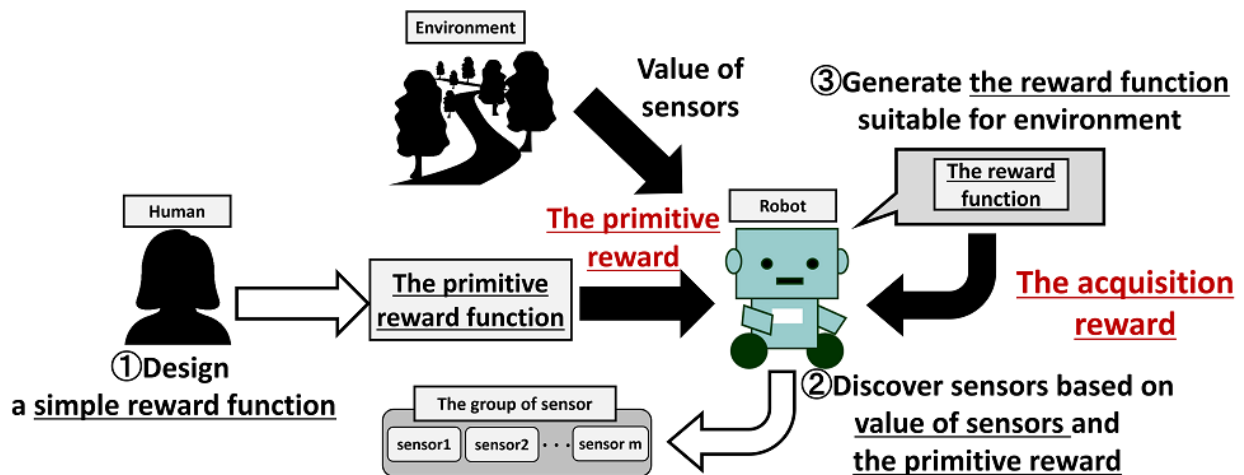


Fig.1 Image on generation the reward function

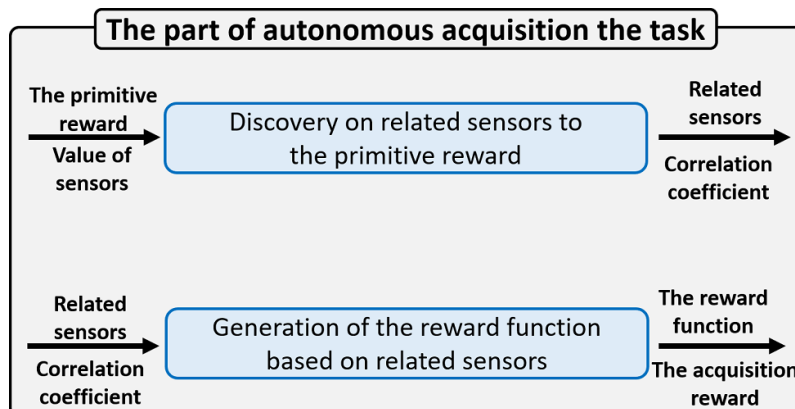


Fig.2 The part of autonomous acquisition the task